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Motivation and Goal

- Validating and comparing the different algorithms for measuring coronal flow velocities
- Assessing the impact of different types of noise in the algorithm accuracy
- Determining the measurements errors (uncertainties)
- Extrapolating the altitude range of previously operated missions
- Goals of the PUNCH mission:
 - ◆ Produce images extending to $\sim 180 R_{\odot}$ to better understand how the mass and energy of the Sun's corona become the solar wind that fills the solar system

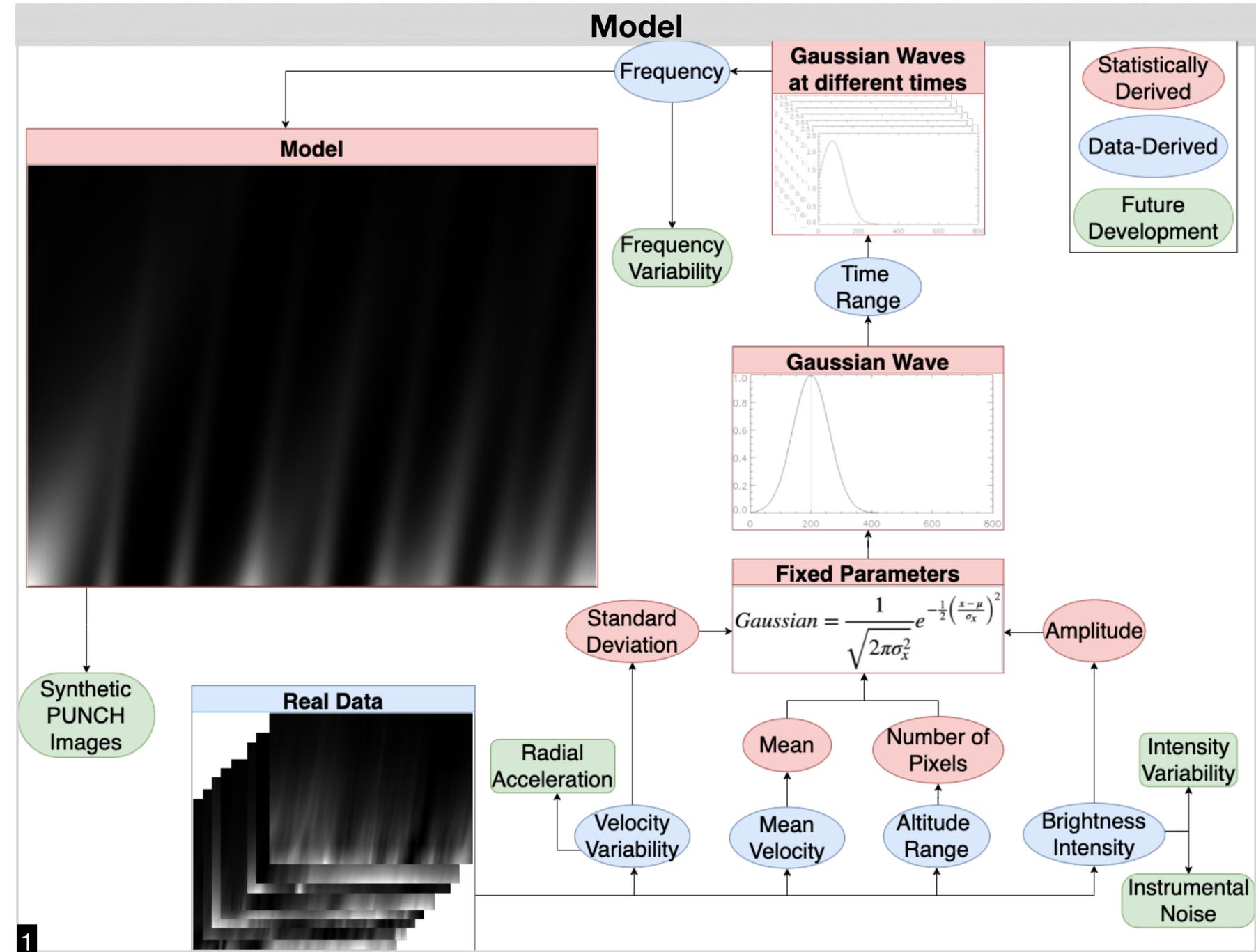


Fig 1. Flowchart of process to create a synthetic corona outflow. In blue, fixed parameters used in our model come from previous observations, such as STEREO-A / COR 2. In red, each parameter controls one aspect of the Gaussian wave, in particular its central position, width and height. In green, features still in development for our model. Our model can easily be extrapolated to altitude ranges of future mission like PUNCH.

Data - STEREO-A / COR 2

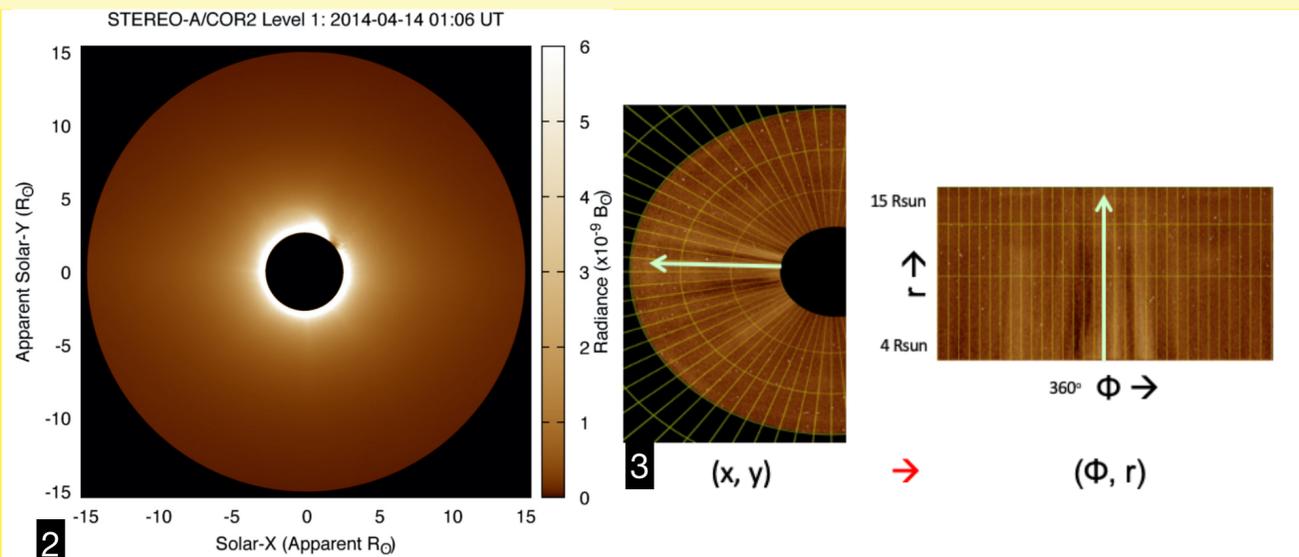


Fig 2. Raw unpolarized long-exposure coronagraph image extracted from SECCHI instrument. Each image was taking every 5 minutes. (Source: [1])

Fig 3. Coordinate transformation from Cartesian (x, y) to polar (ϕ , r). (Source: [2])

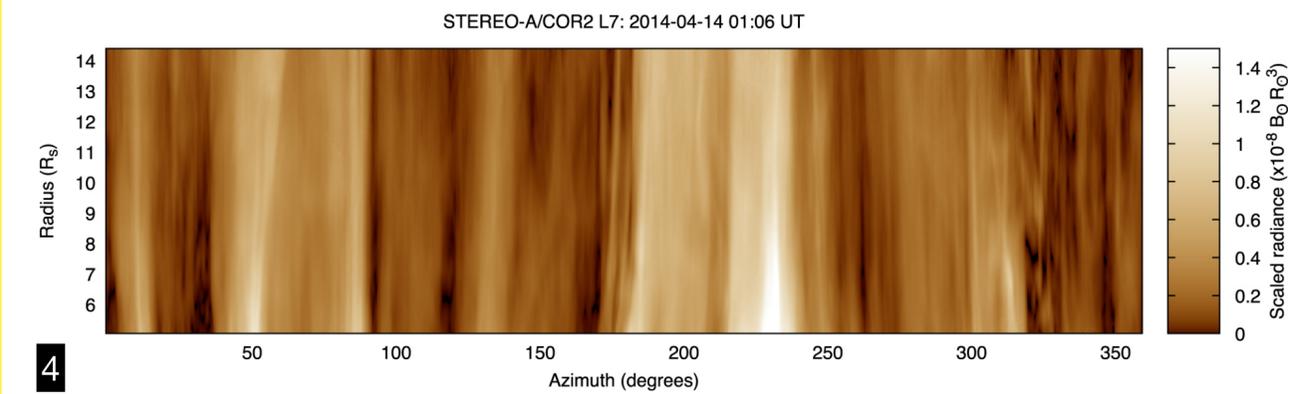


Fig 4. Flow-friendly corona image, is one of the final stages of the image preparation done by Craig DeForest. These had their ad hoc background removed, blur reduced, coordinate resampled and represents a true feature-excess brightness. (Source: [1])

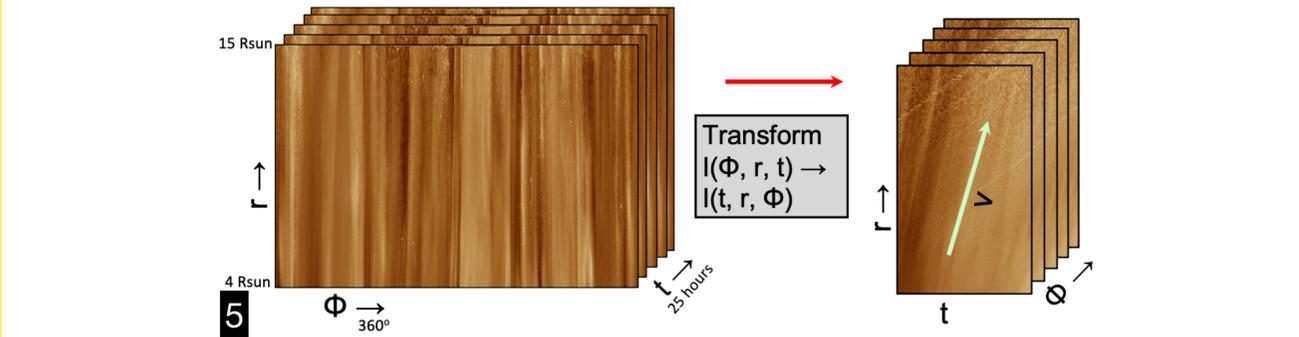


Fig 5. The collection of images at different times allows us to transform the image coordinates from spatial-spatial (ϕ , r) to spatial-temporal (t, r). (Source: [2])

Parameters

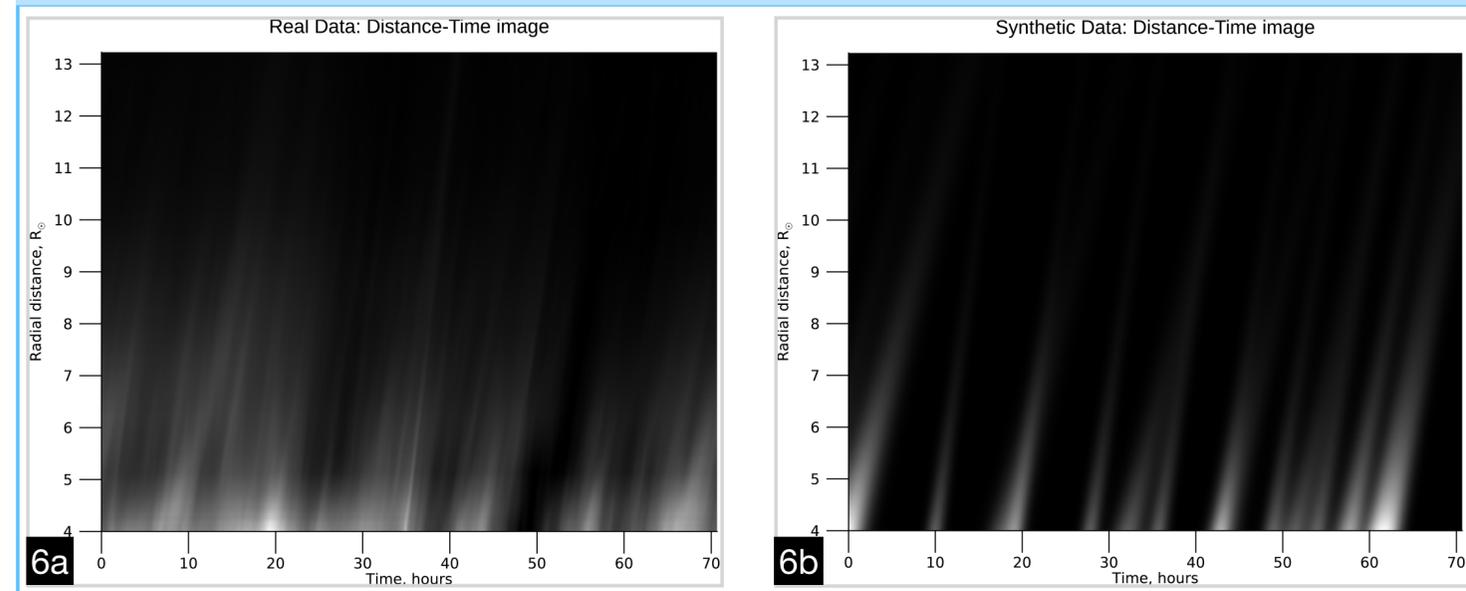


Fig 6. Distance-time arrays. 6a represents the real data, and 6b represents the synthetic data. The synthetic data can mimic the radial behavior, but does not have random noise. A future effort includes an adjustable noise level generated by a random seed.

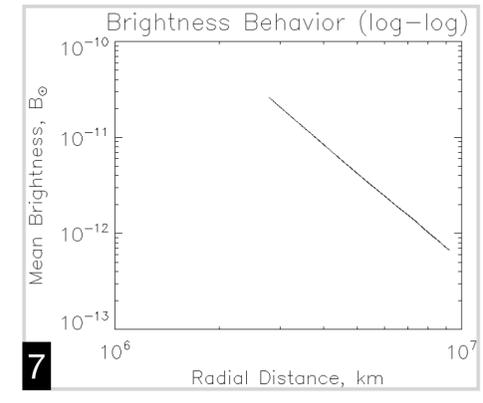


Fig 7. Power-law behavior of the brightness. A simple linear fit of the mean brightness by the cube of the distance indicates the decay.

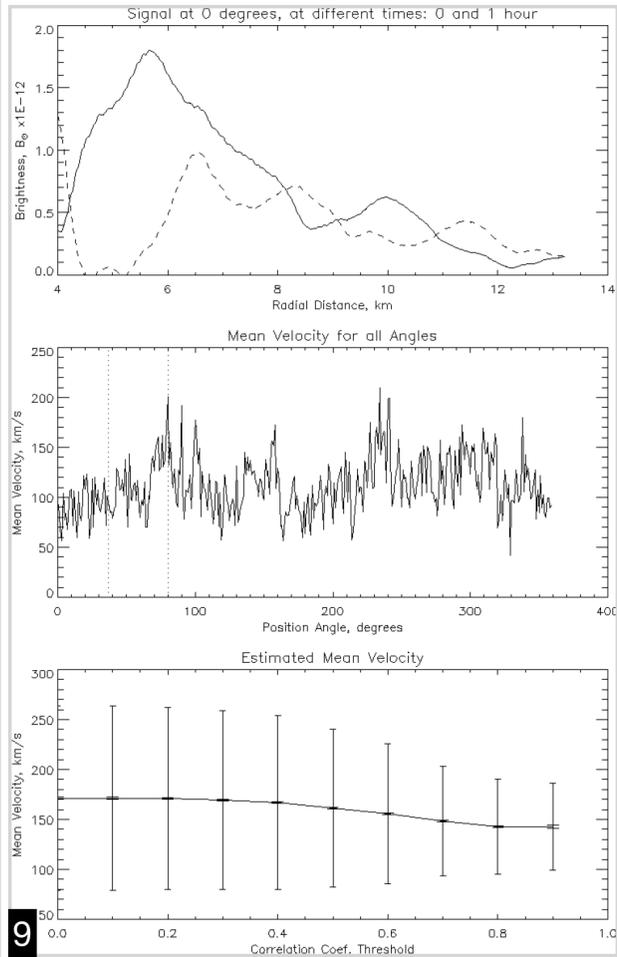
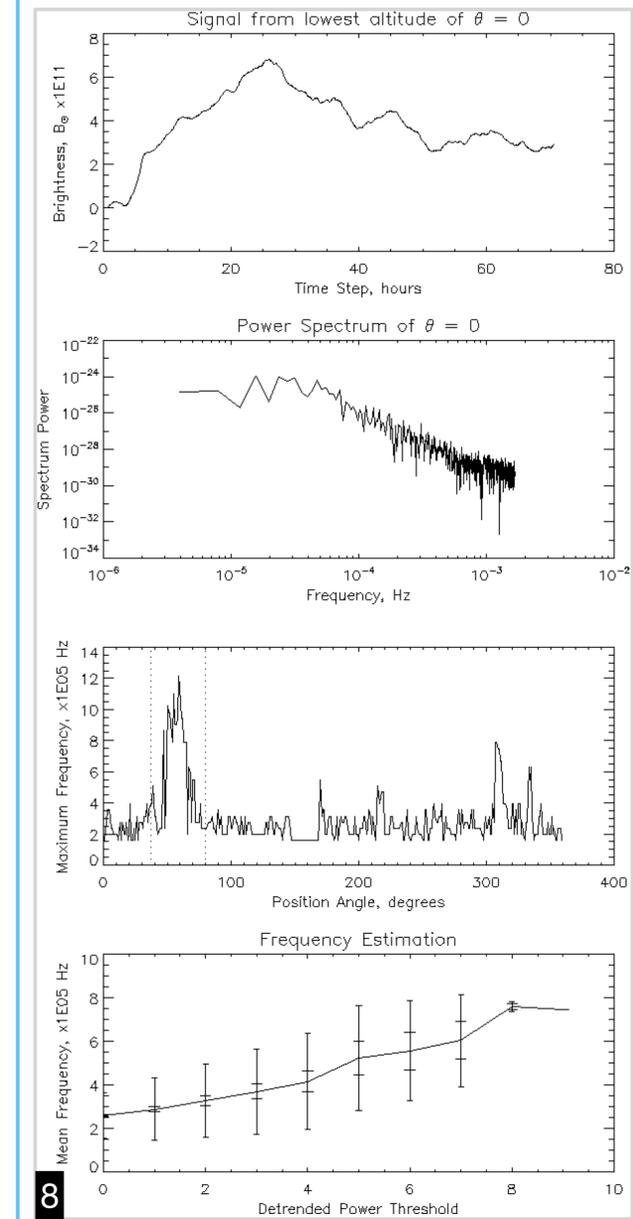


Fig 8. Frequency exploration. The estimated frequency was taken by accounting the maximum frequency for each position angle. This frequency can gauge the amount of features a certain position-time array exhibits.

Fig 9. Velocity exploration. The estimated velocity was obtained using a cross-correlation technique. This velocity could be assessed by any other flow tracking algorithm.

Table 1. Model parameters values. Our synthetic model presented here was produced by using the power-law decay, and the frequency and velocity exploration.

Parameter	Value	Unit
Velocity	173.2	km/s
Velocity Variability	58.4	km/s
Period	4.2	hours
Radial Behavior	-3.0	-

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Flow Tracking Challenge

THE CHALLENGE
Determine the following flow parameters for each model:

- 1) Average radial velocity [km/s] -- primary target
- 2) Velocity uncertainty [km/s]
- 3) Average period of the disturbances [s]
- 4) Uncertainty of the disturbance period [s]

Notations: dt - image cadence, dr - radial pixel size
The DT arrays can be downloaded in two formats (FITS or IDL SAVE).

A warm-up with known propagation parameters
Velocity = 75 km/s, period = 1200 s
dt = 24 s, dr = 435 km

Model 1
dt = 12s, dr = 435 km

Model 2
dt = 12s, dr = 435 km

Model 3
dt = 300s, dr = 9744 km

Model 5
dt = 300s, dr = 9744 km

Model 6
dt = 300s, dr = 9744 km

10a 10b

Fig 10. Website of the Flow Tracking Challenge, and QR code for the page. **10a** represents the challenge description and an example model for testing, and **10b** a collection of model with noise and velocity and frequency variabilities. All models have their sampling time and distance available. The mini-challenge was launched in June. We are inviting all flow trackers and enthusiasts to test their algorithms using our synthetic images. The results will help us to improve our model and to validate the efficiency of the different algorithms.

<https://physics.catholic.edu/faculty-and-research/space-weather-lab/flow-tracking-challenge.html>

Future Plans

- Implement additional features: noises, variability in frequency and brightness
- Include radial acceleration: velocity increasing with altitude
- Integrate realistically a 2D Gaussian wave for spatial-spatial images
- Create a time series of synthetic PUNCH images

References

- [1] DeForest et al., "The Highly Structured Outer Solar Corona", Astrophysical Journal, Vol. 862, 2018.
[2] Thompson et al., "Tracking Flows and Disturbances in Coronagraph Data", AGU, 2018.