







Introduction A new finite-element based variational technique called SAMURAI (Spline Analysis at Mesoscale Utilizing Radar and Aircraft Instrumentation) has been developed in order to integrate aircraft observations from multiple instruments into comprehensive mesoscale composites. SAMURAI analysis can be performed with only a mass continuity constraint to ensure high fidelity to the data, or can incorporate a priori background estimates from a global or other mesoscale analysis.

 $\hat{x}(x, y, z) = \left\{ \rho u, \rho v, \rho w, T', \rho'_a, q'_v \right\}$ $\hat{x}(r,z) = \left\{ \rho r v, \psi, T', \rho'_a, q'_v \right\}$

- Analyze dropsonde, in situ, satellite vector winds, SFMR, and Doppler radar data in inertial frame with or without background
- Thermodynamics analyzed as perturbations to hydrostatic reference state (Dunion 2011)
- Background error covariance modeled by Gaussian recursive filter (Purser et al. 2003)





SAMURAI analysis of pre-depression Karl (2010) on 13 Sept. 00 UTC at 1.5 km altitude. Left panel uses ECMWF as background field for dropsonde analysis, right panel analyzes NOAA P3 Tail Doppler Radar.

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Analysis of Aircraft Observations in Tropical Cyclones Using SAMURAI

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 $J(\hat{\mathbf{x}}) = \frac{1}{2}\hat{\mathbf{x}}^T\hat{\mathbf{x}} + \frac{1}{2}(\mathbf{H}\mathbf{C}\hat{\mathbf{x}} - d)^T\mathbf{R}^{-1}(\mathbf{H}\mathbf{C}\hat{\mathbf{x}} - d)$ $\nabla J(\hat{\mathbf{x}}) = (\mathbf{I} + \mathbf{C}^T \mathbf{H}^T \mathbf{R}^{-1} \mathbf{H} \mathbf{C}) \hat{\mathbf{x}} - \mathbf{C}^T \mathbf{H}^T \mathbf{R}^{-1} d$ $\delta \mathbf{x} = \mathbf{C}\hat{\mathbf{x}} = \mathbf{S}\mathbf{D}\mathbf{F}\hat{\mathbf{x}}$ $S = (P + Q)^{-1}$ $\mathbf{P} = [p_{mm'}]^T,$ $p_{mm'} = \int \phi_m(r)\phi_{m'}(r)dr$ $q_{mm'} = \int_D \epsilon_q(r) \phi_m'''(r) \phi_{m'}'''(r) dr$ $\mathbf{Q} = [q_{mm'}]^T,$ $\phi_m(r) = \Phi\left(\frac{r - r_m}{\Delta r}\right)$ for $m \in M$ and $r \in D$

Analytic Tests and Validation One distinguishing characteristic of the SAMURAI technique compared to other 3DVAR packages is the use of a cubic B-spline basis. The basis is computationally efficient and continuously differentiable to second order, allowing for accurate interpolation to observation locations, flexible incorporation of boundary conditions, and high numerical accuracy of kinematic derivatives. A variety of analytic tests have been performed to ensure accuracy and analysis quality. **Doppler Radar Analysis** In Situ Analysis









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SAMURAI is open source and available by request.

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